

Towards an integrated model of the Western Alps geophysical and geological data: seismic tomography of the Alpine lithosphere by ambient noise tomography and full waveform inversion

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Introduction

To better understand the geodynamic processes of the Alps and the interaction between mantle dynamics and surface structural variations, we aim to build a high-resolution model of the alpine lithosphere using an exceptional dataset including Ocean-Bottom-Seismometers and the most recent methodological developments concerning seismic noise correlations and full waveform inversion (ISTerre).

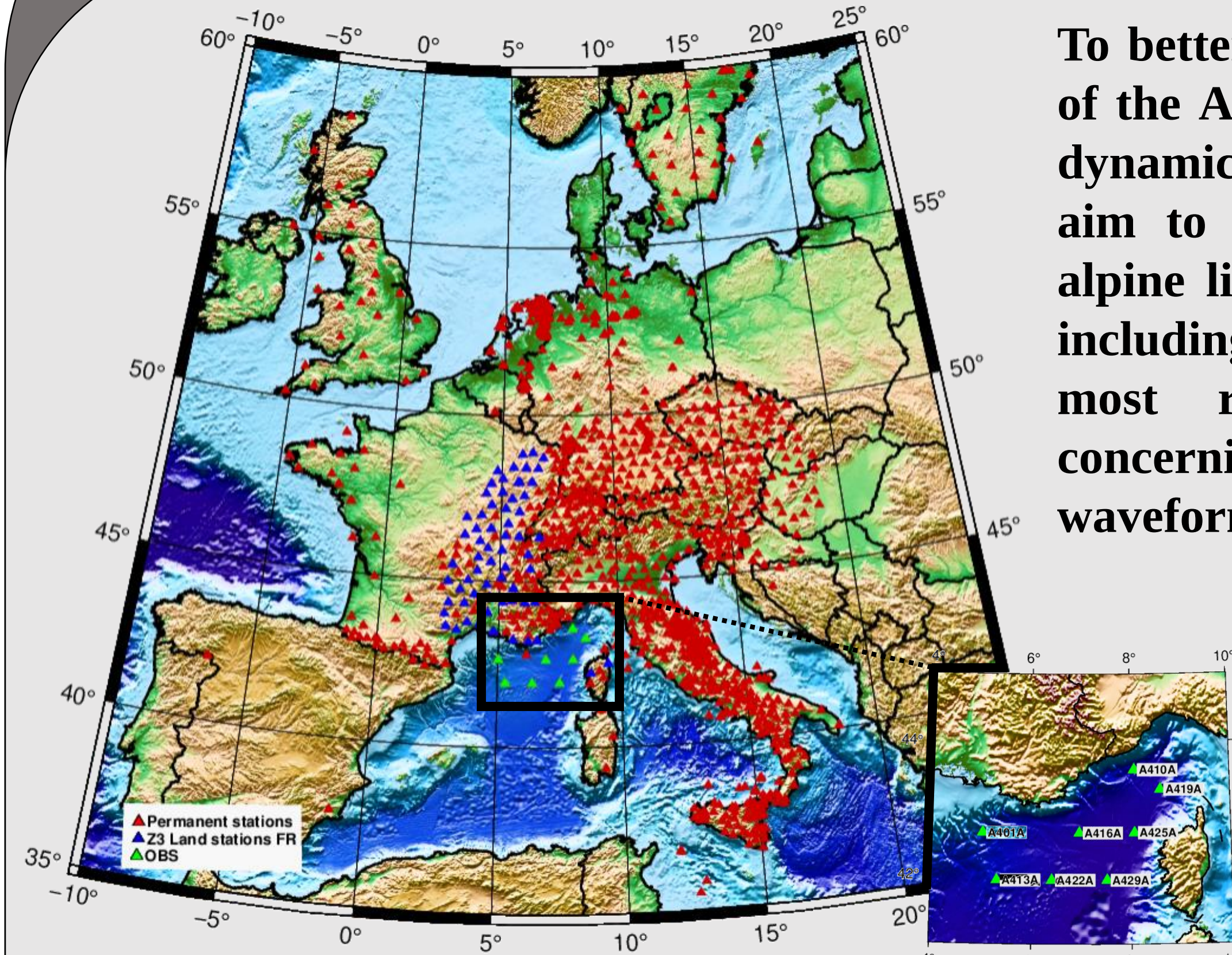


Figure 1. Map of the 1600 broadband seismic stations used in this study

The obtained 3D velocity model will be integrated into a Geomodeller for joint interpretation of geophysical and geological data. This multi-parameter tomography will be an important contribution to the 3-D geological models which is one of the objectives of the "Alps and Peripheral Basins" RGF project.

High-resolution Semi-Bayesian shear wave tomography

- A probabilistic model is obtained by comparing the observed local dispersion curves with the dispersion curves associated with a library of 40 million 1-D Vs models from grid search.
- The Vs probability distribution and the layer boundary presence probability are calculated for each pixel in the 6-50 s period band.
- A unique 3-D shear-wave velocity model is derived from linear inversion of the 100 000 best probabilistic models in 6-80 s.

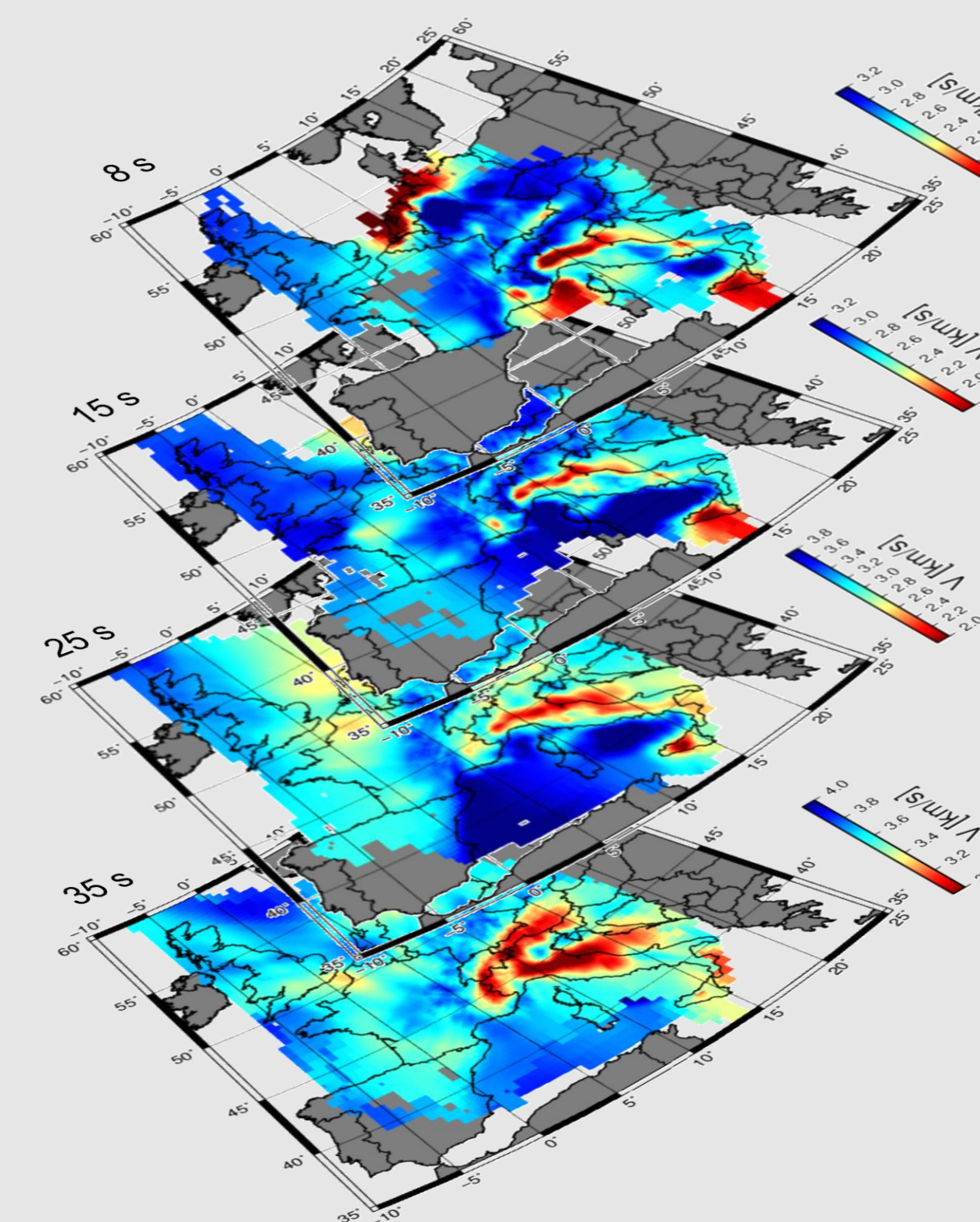


Figure 5. Group velocity maps at 8s, 15s, 25s and 35s

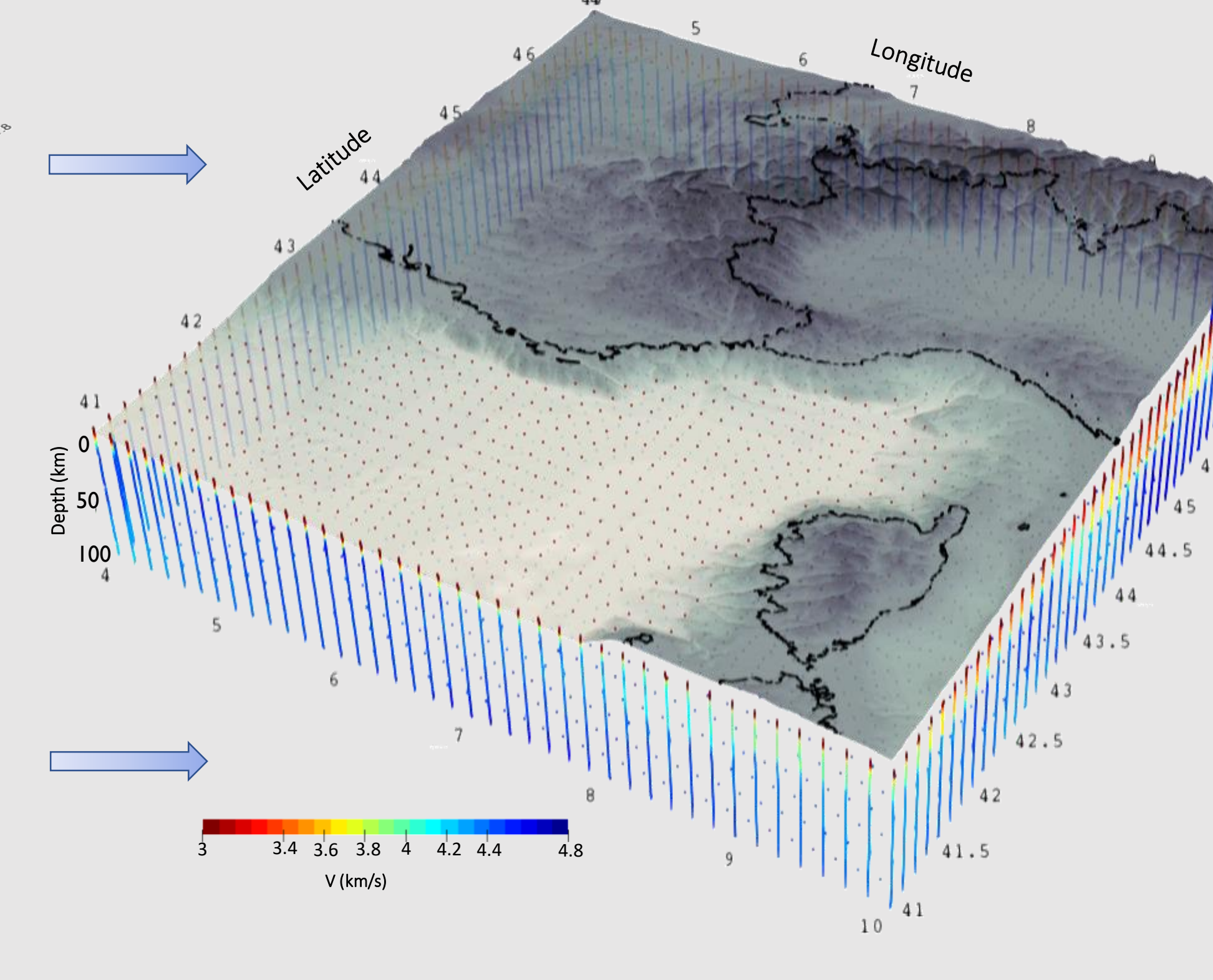


Figure 6. 1-D local Vs models derived from the corresponding dispersion curves and merged in a quasi-3D model

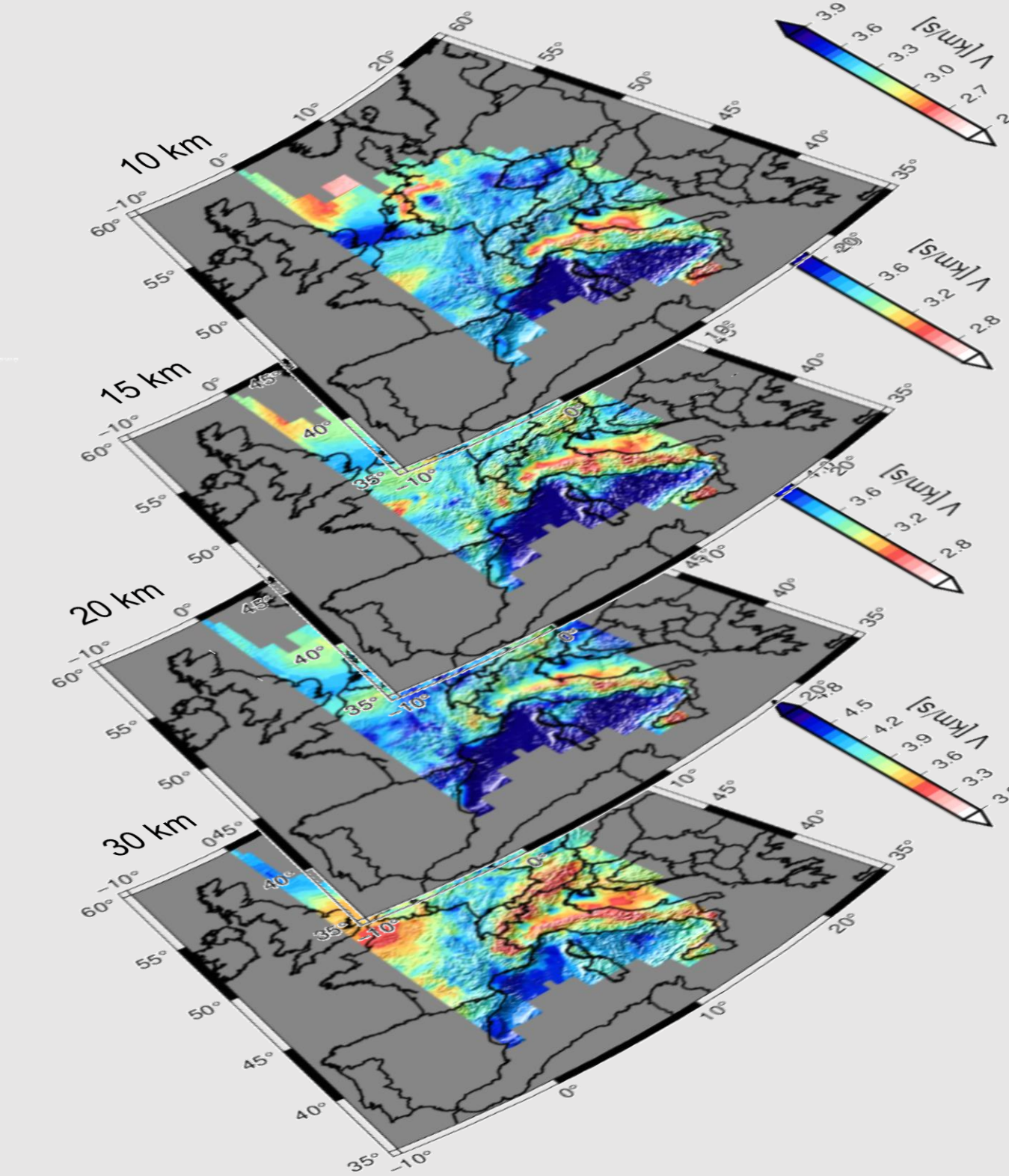


Figure 7. Depth slices in the final 3-D model at 10, 15, 20, 30 km

Surface Wave Group Velocity Tomography

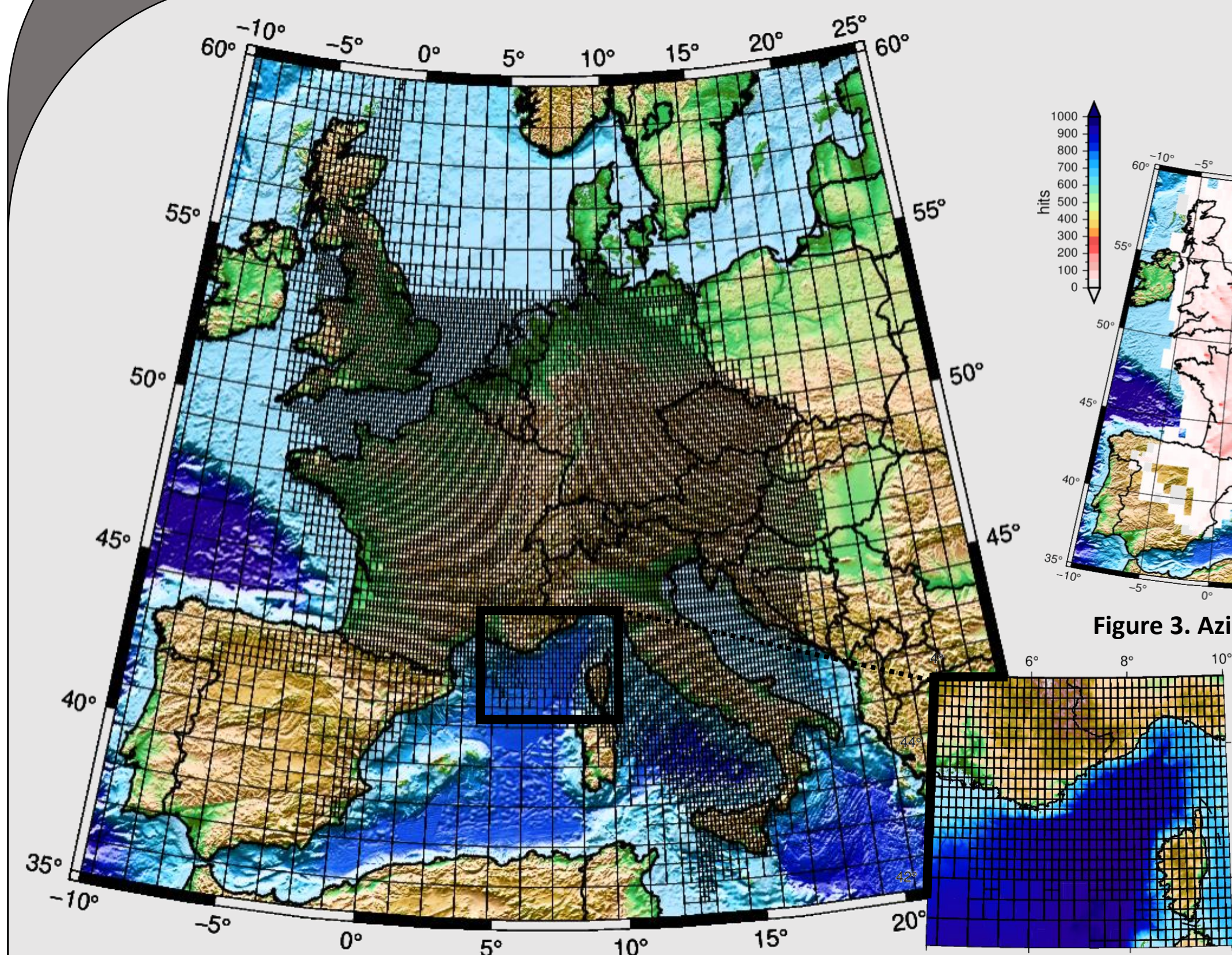


Figure 2. Adaptive grid at 8s period

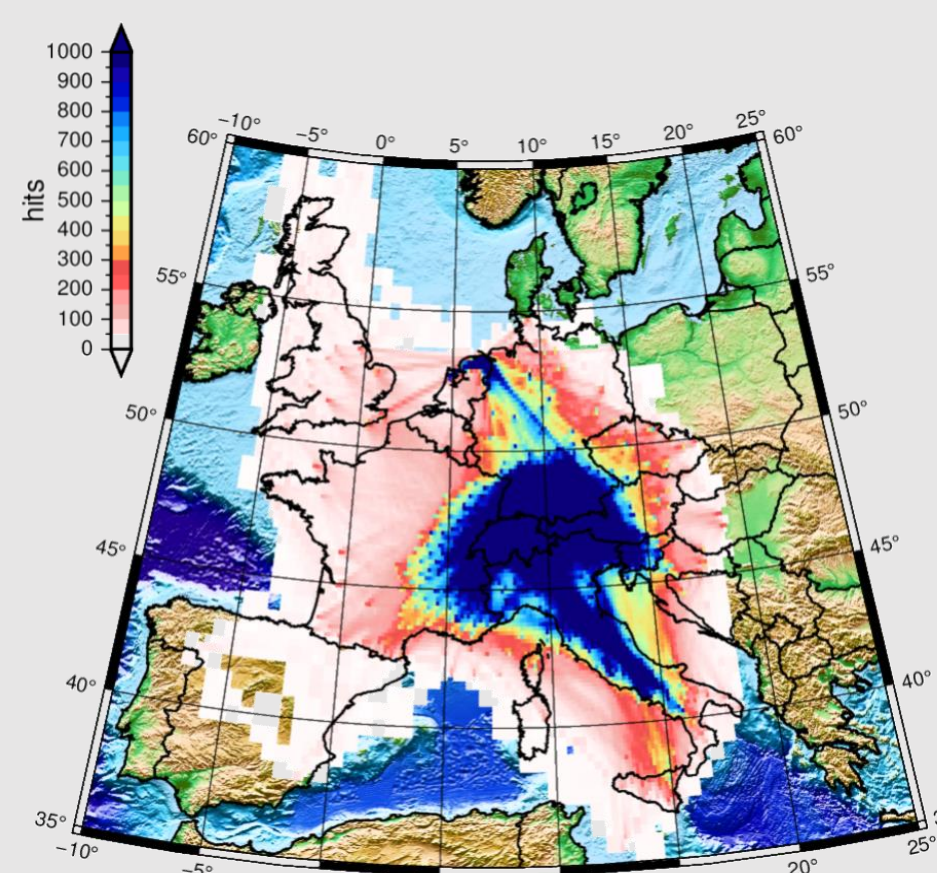


Figure 3. Azimuthal path density at 8s

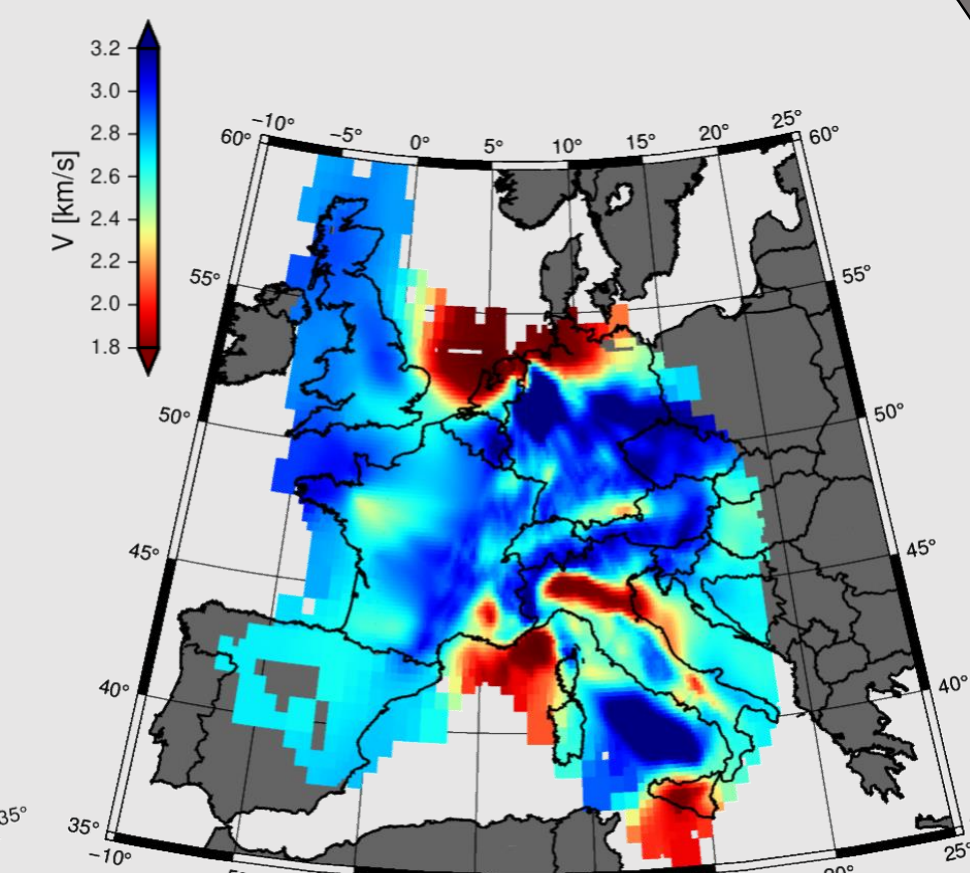


Figure 4. Group velocity map at 8s

- Signals from 3 years of seismic noise (2015-2018) are pre-processed, then correlated and filtered in different period bands.
- The best paths are selected according to distance, SNR and symmetry criteria.
- Over 400 000 individual Rayleigh wave velocity measurements are inverted to 2D group velocity maps between 4s and 80s.
- Automatic pixel-size parameterization is used to obtain the Damped least squares solution.

Misfit function

$$\Phi(m) = (g(m) - d_{obs})^T C_e^{-1} (g(m) - d_{obs})$$

Likelihood function

$$p(d_{obs}|m) = \frac{1}{\sqrt{|C_e|}} \exp\left(-\frac{\Phi(m)}{2}\right)$$

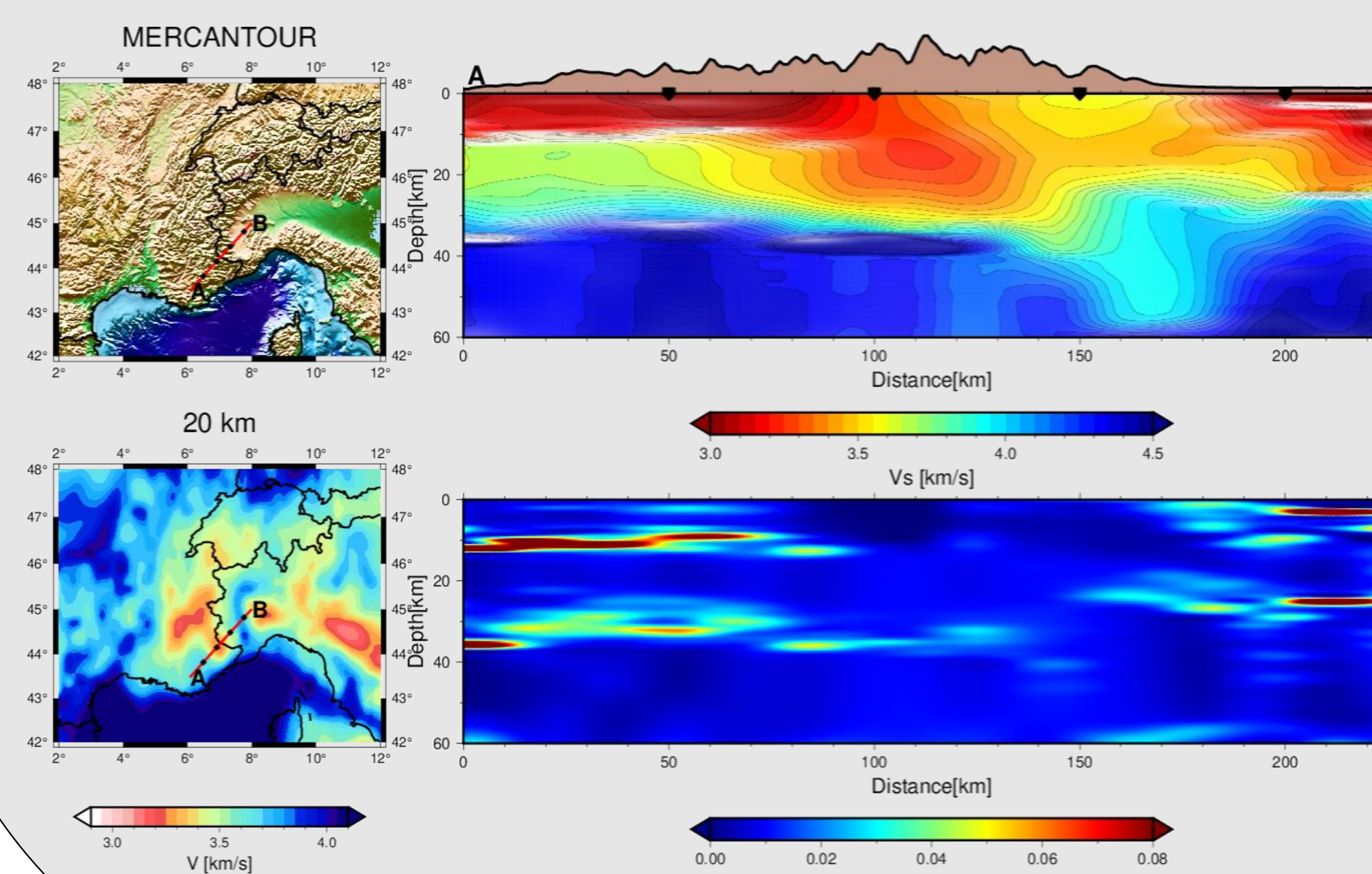


Figure 9. Depth section along the MERCANTOUR seismic profile in the final model

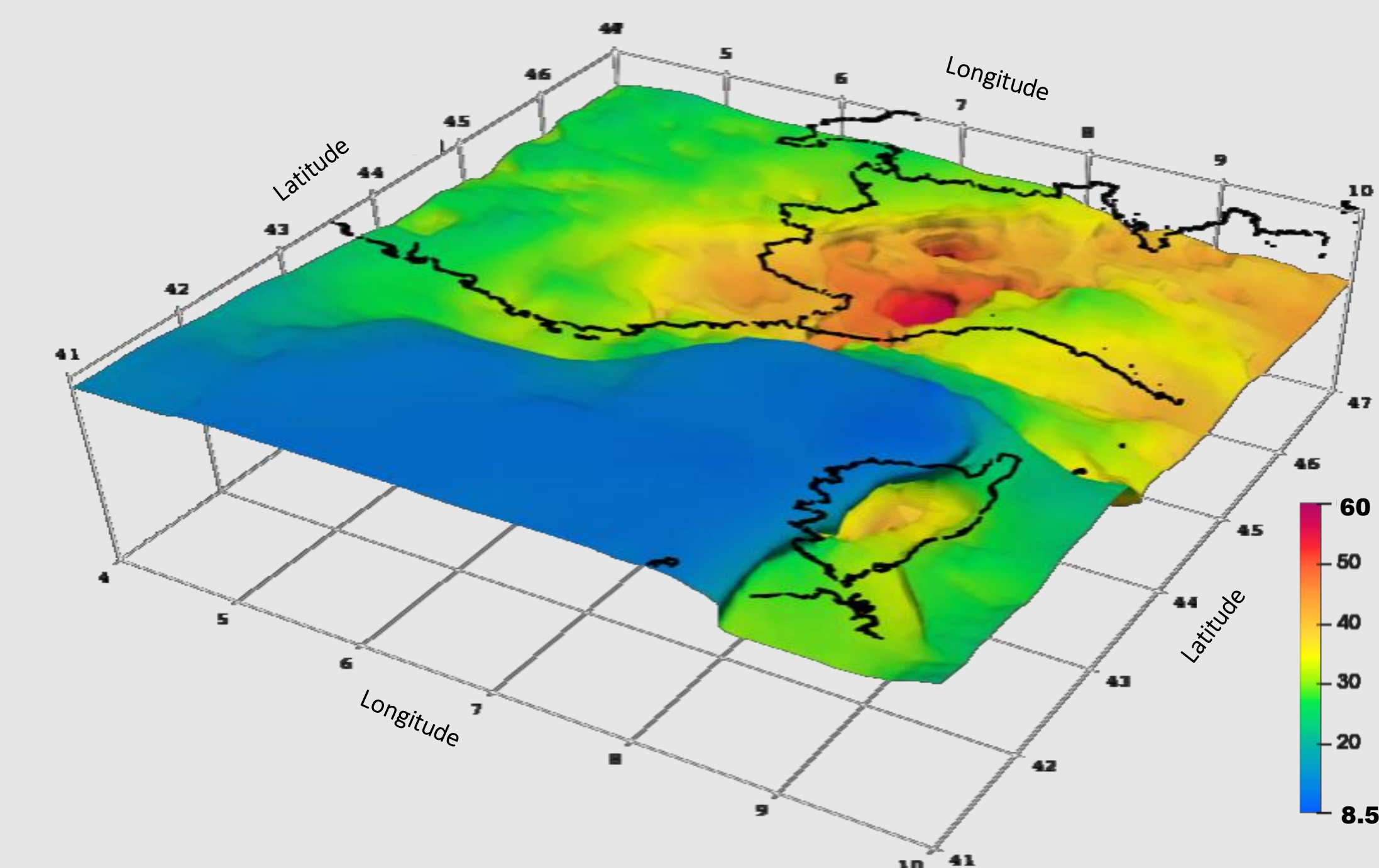


Figure 8. 3-D view of the Moho depth represented as 4.1 km/s isovelocity derived from the final model

Perspectives

- 3-D Vp model from FWI of regional earthquake records with the Vs final model as starting model.
- Integration of geophysical, topographic and geological data in a 3-D lithosphere geomodel of Western Alps using Geomodeller (BRGM).